Enrollment No: _____ Exam Seat No: _____ C.U.SHAH UNIVERSITY **Summer Examination-2017**

Subject Name: Electrical Machine Design - II

	Subject Code: 4TE08EMD1			Branch: B.Tech (Electrical)		
	Semeste	r: 8 Date: 12/	04/2017	Time: 02:30 To 05:30	Marks: 70	
	(2) 1 (3) 1	Use of Programmable c	nain answer bo l figures (if nec	other electronic instrument is pok are strictly to be obeyed. essary) at right places.	prohibited.	
Q-1	a)	Attempt the followin In induction motors, should not be		between the number of stator a	and rotor slots	(14) (1)
	b)	(A) P(C) 5PWhich kind of rotor is run at high speed?		(B) 2P(D) any of the abovee for turbo alternators which an	re designed to	(1)
	c)	(A) salient pole type(C) both (A) and (B)The maximum speed(A)10%	variation in a 3-	(B) non-salient pole type(D) none of the abovephase synchronous motor is(B) 6%		(1)
	d)	(C) 4% Short circuit ratio for (A)0.1 to 0.2	turbo-alternator	(B) 0.2 to 0.4		(1)
	e)	angle should be (A) 9°	erator in order	(D) 0.8 to 0.95to eliminate the fifth harmonic(B) 18°	the chording	(1)
	f)	 (C) 36° The shaft of an induct (A)high speed steel (C) carbon steel 		 (D) 72° ade up of (B) stainless steel (D) cast iron 		(1)
	g)	In synchronous motor (A)Power P (C) P ²	the torque is p			(1)
	h)			displacement between starting	g and running	(1)



i)	The efficiency of a 3-phase induction motor is approximately proportional to		(1)
	(A)s	(B) 1-s	
	$(\mathbf{C}) \mathbf{N}_{\mathbf{s}}$	(D) N	
j)	The ratio of core length to pole pitch for good efficiency is		(1)
0	(A) 0	(B) 0.5	
	(C) 1.5	(D) 1	
k)	The value of slip at full load is determined by the		(1)
	(A) rotor resistance	(B) stator resistance	
	(C) slip	(D) none of the above	
l)	The power factor of a single-phase induction motor is usually		(1)
	(A) unity	(B) lagging	
	(C) always leading	(D) unity to 0.8 leading	
m)	Define the term : total magnetic loading		(1)
n)	Define the term : specific elec	ctrical loading	(1)

Attempt any four questions from Q-2 to Q-8

Q-2	(a) (b)	Attempt all questions Derive the output equation for ac machine. Explain methods for improving starting torque in three phase induction motor.	(14) (7) (7)
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Q-3		Attempt all questions	
	(a)	Explain elimination of harmonics in synchronous machines.	(7)
	(b)	Explain different approaches for computer aided design.	(7)
Q-4		Attempt all questions	(14)
-	(a)	What is Short circuit ratio? Explain effect of SCR on synchronous machine performance.	(7)
	(b)	A 90 kW, 500 v, 50 Hz, 3 phase, 8 pole induction motor has a star connected stator winding accommodated in 63 slots with 6 conductors per slot. If the slip ring voltage on open circuit is to be about 400 V, find a suitable rotor winding,	(7)

stating:

(a) Number of slots (b) number of conductors per slot (c) coil span (d) slip ring voltage on open circuit (e) approximate full load current per phase in rotor. Assume efficiency = 0.9; power factor = 0.86.

Q-5 Attempt all questions

- (a) Explain design of rotor bars and slots of three phase induction motor.
- (b) An 11 kW, 3 phase, 6 pole, 50 Hz, 220 V, star connected induction motor has 54 stator slots, each containing 9 conductors. Calculate the values of bar and end ring currents. The number of rotor bars is 64. The machine has an efficiency of 0.86 and a power factor of 0.85. The rotor mmf may be assumed as 85 percent of stator mm.

Also find the bar and the end ring sections if the current density is 5A/mm².

Q-6 Attempt all questions

(a) What is computer aided design? Explain advantages and limitation of computer (7)



(14)

(7)

(14)

		aided design of machines.	
	(b)	Explain design of damper winding.	(7)
Q-7		Attempt all questions	(14)
	(a)	State some methods to reduce the harmonic torque in induction motors.	(7)
	(b)	Which factors should be considered when estimating the length of the air-gap of the induction motor? Why the air-gap should be as small as possible?	(7)
Q-8		Attempt all questions	(14)
	(a)	Find the main dimensions of a 100 MVA, 11 kV, 50 Hz, 150 r.p.m., 3 phase water wheel generator. The average gap density is 0.65 Wb/m ² and ampere conductors per meter are 40,000. The peripheral speed should not exceed 65 m/s at normal running speed in order to limit the run-away peripheral speed.	(7)
	(b)	Explain design of starting winding for split phase motors.	(7)

